

A

$$y \quad m = \lambda l$$

$$4 \quad I_{O_3} = \int dm r^2 = \int \lambda dr r^2 = \lambda \int_0^l r^2 dr = \lambda \frac{l^3}{3} = \frac{m l^2}{3}$$

$$3/ \quad \vec{\omega} = \dot{\theta} \vec{e}_3$$

$$4 \quad \vec{L}_O = \int_0^l \vec{O} \vec{M} \wedge dm \vec{v}(M) = \int_0^l r \vec{e}_r \wedge \lambda dr r \dot{\theta} \vec{e}_\theta = \lambda \dot{\theta} \vec{e}_3 \int_0^l r^2 dr$$

$$\vec{L}_O = \lambda \dot{\theta} \frac{l^3}{3} \vec{e}_3 = m \frac{l^2}{3} \dot{\theta} \vec{e}_3 = I_{O_3} \vec{\omega} \quad \text{avec} \quad I_{O_3} = \frac{m l^2}{3}$$

$$5/ \quad \vec{O} \vec{G} \begin{vmatrix} \frac{l}{2} \cos \theta \\ \frac{l}{2} \sin \theta \\ 0 \end{vmatrix} \quad \vec{v}_G \begin{vmatrix} -\frac{l}{2} \dot{\theta} \sin \theta \\ \frac{l}{2} \dot{\theta} \cos \theta \\ 0 \end{vmatrix}$$

$$7/ \quad I_G = \lambda \int_{-l/2}^{l/2} dr r^2 = \frac{\lambda}{3} 2 \left( \frac{l}{2} \right)^3 = \frac{\lambda l^3}{12} = \frac{m l^2}{12}$$

$$8/ \quad I_{O_3} = I_G + m d^2 = I_G + m \left( \frac{l}{2} \right)^2 \Rightarrow \frac{I_G}{3} = \frac{I_G}{12} - \frac{m l^2}{4} = \frac{m l^2}{3} \left( \frac{1}{3} - \frac{1}{4} \right)$$

$$I_G = \frac{m l^2}{12}$$

$$9/ \quad \vec{L}_O = \vec{L}^* + \vec{O} \vec{G} \wedge m \vec{v}_G \Rightarrow \vec{L}^* = \vec{L}_O - m \vec{O} \vec{G} \wedge \vec{v}_G$$

$$\vec{L}^* = \frac{m l^2}{3} \dot{\theta} \vec{e}_3 - m \left[ \left( \frac{l}{2} \right)^2 \dot{\theta} \cos^2 \theta + \left( \frac{l}{2} \right)^2 \dot{\theta} \sin^2 \theta \right] \vec{e}_3 = \frac{m l^2}{12} \dot{\theta} \vec{e}_3 = I_G \vec{\omega}$$

$$10/ \quad \text{On retrouve} \quad I_G = m l^2 / 12$$

$$B \quad 11/ \quad \frac{I}{\sigma} = \int_0^R \sigma 2\pi r dr r^2 = 2\pi \sigma \frac{R^4}{4} = \frac{\pi \sigma R^4}{2} = \frac{m R^2}{2} \quad \text{car} \quad m = \sigma \pi R^2$$

$$12/ \quad \vec{\omega} = \dot{\theta} \vec{e}_3$$

$$13/ \quad \vec{v}_{G_1} = \vec{0}$$

$$14/ \quad \vec{v}_{G_2} = \vec{0}$$

$$15/ \quad \vec{0} = \vec{v}_G + \vec{\omega} \wedge \vec{OG} = x' \vec{e}_x + \dot{\theta} \vec{e}_3 \wedge (-R \vec{e}_y)$$

$$= (x' + R \dot{\theta}) \vec{e}_x = \vec{0} \Rightarrow x' + R \dot{\theta} = 0$$

$$16/ \quad \text{Signe } (+) \quad \text{en effet} \quad dx = -R d\theta \quad \text{le disque roule sans glissement}$$